#### University of California, Berkeley College of Engineering Computer Science Division – EECS

Spring 2022

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#### Midterm III SOLUTION April 28<sup>th</sup>, 2022

CS162: Operating Systems and Systems Programming

Your Name:	
SID AND Autograder Login (e.g., student042):	
TA Name:	
Discussion Section Time:	

#### General Information:

This is a **closed book** exam. You are allowed 3 pages of notes (both sides). You may not use a calculator. You have 110 minutes to complete as much of the exam as possible. Make sure to read all of the questions first, as some of the questions are substantially more time consuming.

WRITE ALL OF YOUR ANSWERS IN YOUR ANSWER BOOK, NOT IN THIS BOOKLET! Make your answers as concise as possible. On programming questions, we will be looking for performance as well as correctness, so think through your answers carefully. If there is something about the questions that you believe is open to interpretation, please ask us about it!

Problem	Possible	Score
1	20	
2	18	
3	29	
4	16	
5	17	
Total	100	

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3.14159265358979323846264338327950288419716939937510582097494459230781640628620899

#### Problem 1: True/False and Why [20 pts]

Please *EXPLAIN* your answer in TWO SENTENCES OR LESS (Answers longer than this may not get credit!). Also, answers without an explanation *GET NO CREDIT*.

**Problem 1a[2pts]:** Direct Memory Access (DMA) is "direct" because it accesses devices via memory directly rather than processor instructions.

True False Explain:

DMA is direct because it allows devices to communicate directly with memory without using the CPU at all.

**Problem 1b[2pts]:** If we care about the performance of random accesses to files, it would be better to have a file system with extent-based allocations as opposed to one with linked block-based allocations.

True False Explain:

With extent-based allocations, files are allocated in contiguous chunks, meaning in order to access random parts of the file, you would just need to offset by the specified amount. With linked files, you will need to traverse a linked list of blocks, which will take a time linear in the offset size.

**Problem 1c[2pts]:** For Project 3, read, write, and remove syscalls should not be supported on directories since there are <u>dedicated</u> directory syscalls readdir, mkdir, and rmdir.

True False

Explain:

remove should still be supported on directories. rmdir is not a supported syscall in Project 3.

**Problem 1d[2pts]:** For Project 3, a struct inode\_disk filled fully with indirect pointers would be a valid approach to support the maximum file size of 8 MiB.

True False

Explain:

While this is just enough to meet the maximum file size since  $2^7 \times 2^7 \times 2^9 = 2^{23} = 8$  MiB, struct inode\_disk needs to store other metadata (e.g. length, magic number).

**Problem 1e[2pts]:** A solution to the General's Paradox is sending large numbers (100's) of messengers in each direction to guarantee a messenger gets through to the other side.

True False Explain:

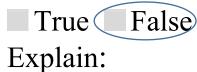
While sending more messengers will reduce the likelihood of a failed delivery, the General's Paradox still cannot be solved. The network remains unreliable.

**Problem 1f[2pts]:** If our file system is prone to short-lived files, we should implement a write-back cache as <u>opposed</u> to a write-through cache.



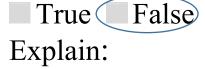
Temporary files created and destroyed before flushing of the cache may avoid having unnecessary disk writes.

**Problem 1g[2pts]:** The File Allocation Table and Fast File System can both support soft and hard links.



FAT cannot support hard links as all metadata for a file is stored in the directory entry. FAT cannot support soft links either due to the lack of a directory entry field marking the file as a link.

**Problem 1h[2pts]:** In most systems, waiting time scales linearly with respect to utilization.



Other overhead costs, no matter how small, will add up especially with high utilization, resulting in the non-linear relationship.

**Problem 1i[2pts]:** Just like any other I/O, NFS servers require invocations of open and close syscalls.

True False Explain:

While NFS does not require the client to make network open and close calls, the server still needs to perform these to be able to perform an I/O operation.

**Problem 1j[2pts]:** For Project 3, each process is created from another process, meaning all processes are children of the very first process. Since the very first process is initialized with the root directory as its current working directory (CWD), processes can't have a CWD besides the root directory.

True False Explain:

chdir can be used to change the CWD of a process.

# Problem 2: Multiple Choice [18pts]

Choose *all* that apply.

**Problem 2a[2pts]:** For which situations would you require synchronization to resolve race conditions in Project 3? Only consider synchronization at that abstraction level, not below.

- Simultaneous resizing of different inodes.Changing metadata fields in the inode.Adding directory entries to a directory.
- ① Calling file\_deny\_write on a file.
- E: None of the above.

**Problem 2b[2pts]:** What are some advantages of SSDs over HDDs?

- A Random reads are faster.
- B: Higher durability over many write operations.
- C: Cost per byte of memory is lower.
- No moving parts, so more physically durable.
- E: None of the above.

**Problem 2c[2pts]:** Which of the following could be used in HDDs to improve performance?

- (A) Increase disk rotation speed.
- B: Internal caching.
- C: Track skewing.
- ① Internal scheduling algorithms such as a simple elevator algorithm.
- E: None of the above.

Problem 2d[2pts]: Which of the following are true regarding device access schemes?

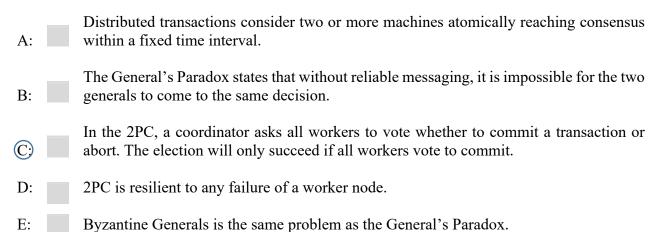
- A: Port-mapped I/O memory-mapped I/O, and DMA are all forms of programmed I/O.
- (B) Memory-mapped I/O uses standard memory instructions such as load and store.
- C: Memory-mapped I/O uses a distinct memory space separate from physical memory.
- D: DMA maps control registers and display memory directly to physical memory.
- E: None of the above.

E:

**Problem 2e[2pts]:** Which of the following are true about the ACID properties for transactions? A: Atomicity means that each action within the transaction must be atomic. B: Consistency means that data must be consistent across all disks even with RAID. (C) Isolation means that transactions appear to be serialized. (D) Durability means that a transactions' committed changes must persist through crashes. E: None of the above. **Problem 2f[2pts]:** Which of the following are true about Project 3? (A) The cache can coalesce writes into a single disk operation. B: The path / . . / . . is considered invalid. C: The buffer cache contains file data blocks, inode\_disk structs, and inode structs. (D) Different file descriptors can reference the same inode. E: None of the above. **Problem 2g[2pts]:** Which of the following strategies are valid ways to detect congestion in a network? Increases in packet round time. (A) (B:) Dropped packets. C: Sender has not received ACK from receiver. D: Query the ISP's congestion API. E: None of the above. **Problem 2h[2pts]:** Select all of the following that are true about networking. A: Sockets can only be used to communicate between two different machines. B: Congestion control avoids overflowing the receiving buffer of the destination server. C: MAC addresses are assigned by your ISP. (D) TCP does not provide guarantees on latency of bytes being delivered.

Packet loss in a network is the result of network congestion.

**Problem 2i[2pts]:** Select all of the following that are true about distributed transactions: (*choose all that apply*):



## Problem 3: Short Answer [29pts]

Please write your answer in <u>THREE SENTENCES OR LESS</u> (Answers longer than this may not get credit!).

**Problem 3a[3pts]:** Consider a network file system backed by hard drives with the following parameters.

- Network latency (RTT): 10 ms
- Disk seek latency: 3 ms
- Disk rotational speed: 6000 RPM
- Network bandwidth: 50 sectors/10 ms
- Disk controller latency: 1 ms
- Disk transfer speed: 100 MB/s

What is the average latency to read 50 sequential 4 KB sectors (in a single network request) from this network file system? Assume there are no other pending requests to the system, and the CPU processing overhead is negligible.

The queuing latency is 0 ms since there are no other pending requests. Average latency can be calculated with  $\frac{1}{2} \times (60000 \text{ ms/min} / 6000 \text{ RPM}) = 5 \text{ ms}$ . Transfer latency will be  $50 \times 4 \text{ KB} / 100 \text{ MB/s} = 2 \text{ ms}$ . Adding these with the network latency (10 ms), controller latency (1 ms), and seek latency (3 ms) gives 21 ms.

**Problem 3b[3pts]:** Using Little's Law, what is the maximum amount of inflight data in a network? Explain. Note that this question is unrelated from the previous.

The maximum amount of inflight data in a network is the bandwidth-delay product, n = B \* RTT where B is the bandwidth and RTT is the round-trip time.

**Problem 3c[3pts]:** Is Two Phase Commit subject to the General's Paradox?

No. The General's Paradox requires consensus at the same time while 2PC considers eventual consensus.

**Problem 3d[3pts]:** Consider a TCP network implemented over the US Postal Service. The RTT latency to send a packet/letter from Berkeley, CA to Cambridge, MA is 2<sup>18</sup> seconds (3 days). Each packet/letter can store 32 KiB of written text. If we use the stop-and-wait protocol, what is the bandwidth of this network in bits per second? Explain.

With stop-and-wait, this network will have 1 packet per RTT. Each packet is 2^15 bytes or 2^18 bits divided by 2^18 seconds which yields 1 bit per second.

**Problem 3e[3pts]:** For project 3, you are using a static array for your buffer cache with a clock algorithm for eviction. What metadata should each cache block in the buffer cache have, and what should that metadata be initialized to? Explain.

Each cache block needs a dirty bit (for write back), valid bit (for initialization), and use bit (for clock) which should all be initialized to 0.

**Problem 3f[2pts]:** What is the major drawback of polling strategies versus I/O interrupts?

Polling wastes CPU cycles for infrequent I/O operations.

**Problem 3g[3pts]:** Consider a system using RAID 5. Ignoring any metadata operations (e.g. inode accesses) and assuming no cache, how many disk I/O operations must occur when updating a data block? Explain.

4. Both the data block (D) and parity block (P) need to be read in. Then, the old data is "removed" from the parity block with  $P_{tmp} = P \oplus D$ . The new parity block  $P_{new} = P_{tmp} \oplus D_{new}$ . Finally, the the new data block ( $D_{new}$ ) and new parity block ( $P_{new}$ ) are written back to disk.

**Problem 3h[3pts]:** 3D XPoint is an emerging memory technology that provides persistent storage with near-DRAM throughput. 3D XPoint supports updating blocks in-place. How does this simplify an SSD's FTL firmware?

Erasure blocks are no longer necessary. On a write, the FTL doesn't need to write the block to another page and update the mapping but rather can update the block in place.

**Problem 3i[3pts]:** Give a *specific* example why the End-to-End Principle says that reliable file transfer should be implemented at end hosts and not in the network.

Even if implemented perfectly in the network, the end hosts still need to check since there can be hardware faults, mistakes in file transfer programs or data communication system, or hardware processors in either end hosts.

**Problem 3j[3pts]:** Journaling file systems require data to be written twice. How can the file system optimize for good response time? How about good throughput? Explain.

Journaling file systems can use asynchronous write back, meaning changes will not immediately be applied to disk on a commit. This allows for a good response time since committing a transaction simply involves writing a small commit entry to a sequential log. To optimize for good throughput, the file system can batch write-backs to schedule disk accesses more efficiently than immediate individual or small groups of writes.

## Problem 4: Pintos Logs [16pts]

Gojo Satoru decides to add logging to Pintos. He plans for the log to be a fixed contiguous collection of blocks (on disk) in the following format. Each row shown is of BLOCK\_SECTOR\_SIZE.

```
Header block
block A
block B
...
```

You are given the following methods and data structures.

```
/* Log */
struct log {
 uint32 t size;
                       /* Size of log (in number of sectors). */
 block_sector_t start; /* Starting block number of log (i.e. header block). */
 struct logheader lh; /* In-memory copy of the log header block. */
};
/* Log header */
struct logheader {
                        /* Number of blocks used in log excluding header. */
 uint32 t n;
 block_sector_t block[BLOCK_SECTOR_SIZE / 4 - 1];
static struct log log; /* In-memory representation of log, initialized at boot. */
#define BLOCK SECTOR SIZE 512
struct block* fs device;
void block_read(struct block* block, block_sector_t sector, void* buffer);
void block write(struct block* block, block sector t sector, void* buffer);
```

For instance, consider the following transaction.

- 1. Write all 0's to the block at block sector t 2000,
- 2. Write all 1's to the block at block sector t 2500,

The log would look like.

```
struct logheader lh = {2, {2000, 2500, ...}};

0000000000...

111111111...
...
```

Gojo also makes the following design decisions:

- The log can only contain at most one transaction at a time.
- Instead of writing a commit message to the log, a transaction is considered committed when the header block is written to disk.
- All file system syscalls hold the global file system lock for simplicity.
- There is no buffer cache.

With logging, a typical file system syscall will look like the following.

```
lock_acquire(&fs_lock);
...
/* Perform syscall but use log_read/log_write instead of block_read/block_write. */
...
commit();
lock_release(&fs_lock);
```

**Problems 4a-4m[1pt each]:** Help Gojo implement this logging system. Only one piece of code should be written per blank (i.e. no multiple statements with semicolons and no blank lines). Use proper C syntax with the given APIs. Pseudocode or comments will not receive any credit. You may only use methods and data structures given in this question as well as built-in ones (i.e. libc). You may also ignore any memory leaks if applicable.

```
/* Read the log header from disk into log.lh. */
static void read_head(void) {
 block_read(fs_device, log.start, &log.lh);
/* Write log.lh to the log header on disk. */
static void write_head(void) {
 block_write(fs_device, log.start, &log.lh);
}
/* Add an entry to the log to represent the action "write BUFFER to the block at
   SECTOR." Assume read head has already been called. */
void log_write(block_sector_t sector, void* buffer) {
  /* Check if block already in log. */
 for (int i = 0; i < log.lh.n; i++) {
    if (log.lh.block[i] == sector){
      block_write(fs_device, log.start + i + 1, buffer);
      return;
    }
  }
 log.lh.block[log.lh.n] = sector;
 block_write(fs_device, log.start + log.lh.n + 1, buffer);
 log.lh.n++;
}
```

```
/* Read the block at SECTOR from disk. If the log contains an updated version of
   the block, read that instead. Assume read_head has already been called. */
void log_read(block_sector_t sector, void* buffer) {
  /* Check if block already in log. */
 for (int i = 0; i < log.lh.n; i++) {
    if (log.lh.block[i] == sector) {
      block_read(fs_device, log.start + i + 1, buffer);
     }
 block read(fs device, sector, buffer);
/* Copy committed blocks from log to their home location. */
static void install_trans(void) {
 uint8_t* data = malloc(BLOCK_SECTOR_SIZE);
 for (int i = 0; i < log.lh.n; i++) {
    block_read(fs_device, log.start + i + 1, data);
    block_write(fs_device, log.lh.block[i], data);
 }
}
/* Commit transaction to disk and clean up. */
static void commit() {
  if (\log.1h.n > 0) {
    /* Commit and apply transaction. */
    write head();
    install_trans();
    /* Clear the log. */
    log.lh.n = 0;
   write head();
 }
}
```

**Problem 4n[3pts]:** Suppose Gojo's computer crashes unexpectedly. When Gojo powers up his computer again, how can the OS tell if the transaction stored in the log has been committed? Provide a clear criteria and explain.

On reboot, it suffices for the OS to read the header block of the log. If log.lh.n != 0, then the transaction has been committed. This is because a transaction is committed once the header block is written to disk (with log.lh.n > 0) and discarded when log.lh.n is set to zero.

## Problem 5: Filesystem Design [17 pts]

Tony Stark has hired you to create a file system to store the designs for his newest Iron Man suit. He would like to use 32-byte sectors and 2-byte disk pointers. Blocks and sectors may be used interchangeably throughout this question.

**Problem 5a[2pts]:** Tony wants to optimize for a workload where each file is accessed as a whole (i.e. the entire file is read in). Most of Tony's files are really large (but is still within max file size). Given the choice between FAT and FFS, which would be better suited for minimizing access time for the given workload? Explain.

A case could be made for either. FAT will require less disk accesses since the FAT array itself is stored in a single sector, so it only needs to read in that and all the actual data sectors. On the other hand, FFS will need to traverse through various levels of indirect pointers, incurring more disk accesses. However, later versions of FFS (e.g. BSD 4.2) added optimizations for disk performance such as block groups which could give a better access time than FAT.

**Problem 5b[3pts]:** You first consider using a filesystem with indexed inodes. Each inode will contain 2 bytes of metadata. Given that each inode must fit exactly into a single sector, how many direct, indirect, and doubly indirect pointers should you use to support a maximum file size of exactly 10,560 bytes? Explain.

The inode has 2 B of metadata, so it can fit at most 30 B / 2 B = 15 pointers (of any type). For each indirect/doubly indirect block, there are 32 B / 2 B = 16 direct/indirect pointers. Therefore, we can fit one doubly indirect pointer which points to  $16 \times 16 \times 32$  B = 8,192 B. This leaves us to fill 2,368 bytes. An indirect pointer can point to  $16 \times 32$  B = 512 B, so we can fit 4 indirect pointers. This leaves us with 320 B to fill with direct pointers, which can be covered by 10 direct pointers. This gives us 10 + 4 + 1 = 15 pointers total, fitting perfectly inside the inode with the metadata.

For 5c-5e, the indexed inode system you are considering will have 12 direct pointers, 2 indirect pointers, and 1 doubly indirect pointer. **Note that this is may be a different design with regards to the pointer breakdown from the previous part**. You are working with a 9,600 byte file called jarvis.txt.

**Problem 5c[3pts]:** Assuming the file number is known (i.e. directory lookup not required), how many disk sectors would need to be accessed to read the last byte of jarvis.txt with the indexed inode system? Explain.

Using similar calculations as Problem 5b, we can see that 9,600 is the max file size. As a result, first the inode is read in, then the doubly indirect block, then the indirect block, then the data block, incurring a total of 4 disk accesses.

**Problem 5d[3pts]:** Assuming the file number is known (i.e. directory lookup not required), how many disk sectors would need to be accessed to read the last byte of jarvis.txt file with FAT? Explain.

The FAT array is of size  $2^{16} \times 2$  B =  $2^{17}$  B =  $2^{12}$  sectors. The file takes up up 9,600 B / 32 B = 300 sectors, so we have to read 300 sectors (in the worst case) to traverse through the FAT array. Then, one sector needs to be read in for the actual data.

**Problem 5e[3pts]:** With the indexed inode system, what fraction of the disk space used by jarvis.txt is for the data? Explain. Leave your answer in an unsimplified fraction.

There are a total of 1 (inode) + 2 (indirect blocks from the indirect pointers) + 1 (doubly indirect block) + 16 (indirect blocks from the doubly indirect pointer) = 20 sectors = 640 B that don't correspond to data. This means the actual data only takes up 9600 / (9600 + 640) = 0.9375 of the disk.

**Problem 5f[3pts]:** You move on to making the system reliable. Assume there are 5 disks worth of data. You consider using either RAID 1 or RAID 5 to store your data across these disks. Disk space is expensive, so Tony wants to spend the least amount of money necessary. Which method, between RAID 1 or RAID 5, would minimize the number of extra disks needed? Explain.

Since Tony has 5 disks worth of data, RAID 1 would require 5 extra disks due to each disk needing to be mirrored. However, RAID 5 will require just one extra disk since it uses parity blocks instead of a full mirror.

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